1. Follow line to first block then stop

2. Move arm forward and open claw.

3. Make the 90o turn.

4. Line tracking code again, stop at second block.

5. Scan environment for highest light sensor read (lowest is brightest) and record encoder values at the brightest.

6. Make wheels return to that position.

7. Move 5cm away, get the light and retract the claw.

8. Turn to find next line.

9. Line tracking again.

10. Turn 90o again.

11. Drive straight to drop off point.

12. Extend arm and release.